Symmetries in Physics Lecture 7

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Lecture contents

Chapter 2. Continuous symmetry groups

▶ II.1. Abelian groups: SO(2) and T(3)

- ▶ II.2. The rotation group *SO*(3)
- ▶ II.3. The group SU(2)
- ▶ II.4. The Euclidean group E_3

Properties of the Clebsch-Gordan coefficients

Angular momentum selection rule: $\langle mm'(jj')JM \rangle = 0$ unless m + m' = M and $|j - j'| \le J \le j + j'$.

Orthogonality and completeness:

$$\sum_{m,m'} \langle JM(jj')mm' \rangle \langle mm'(jj')J'M' \rangle = \delta_{J'}^J \delta_{M'}^M,$$
$$\sum_{JM} \langle mm'(jj')JM \rangle \langle JM(jj')nn' \rangle = \delta_n^m \delta_{n'}^{m'}.$$
(1)

Symmetry relations:

$$\langle mm'(jj')JM \rangle = (-1)^{j+j'-J} \langle m'm(j'j)JM \rangle = (-1)^{j+j'-J} \langle -m, -m'(jj')J, -M \rangle = (-1)^{j-J+m'} \langle M, -m'(Jj')jm \rangle \sqrt{\frac{2J+1}{2j+1}}.$$
 (2)

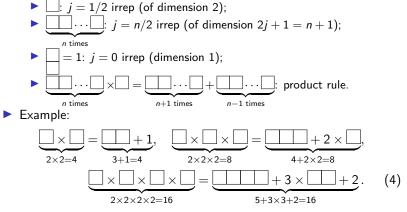
Explicitly, the direct product and irreducible representations are related through:

$$D_{j}(R)^{m}{}_{n}D_{j'}(R)^{m'}{}_{n'} = \sum_{J,M,N} \langle mm'(jj')JM \rangle D_{J}(R)^{M}{}_{N} \langle JN(jj')nn' \rangle,$$

$$\delta^{J}{}_{J'}D_{J}(R)^{M}{}_{M'} = \sum_{m,m',n,n'} \langle JM(jj')(mm') \rangle D_{j}(R)^{m}{}_{n}D_{j'}(R)^{m'}{}_{n'} \langle nn'(jj')J'M' \rangle.$$
(3)

II.2.12. Direct product decomposition using Young tableaux

The decomposition into irreps of the direct product of j = 1/2 representations of SO(3) [more specifically, of SU(2)] can be obtained using Young tableaux, using the following rules:



The exact decomposition of the direct product basis into constitutive irreps must be performed explicitly, e.g. by explicit construction or using projector operators.

II.2.13. Irreducible tensors

- Def: A set of operators {O^s_λ, λ = −s, −s + 1,...s} form the components of an *irreducible spherical tensor* of angular momentum s if U(R)O^s_λU(R⁻¹) = ∑_{λ'}O^s_{λ'}D_s(R)^{λ'}_λ.
- Theorem: The comps. of an irreducible sph. tensor satisfy:

$$\begin{aligned} [\mathbf{J}^2, O^s_{\lambda}] &= s(s+1)O^s_{\lambda}, \qquad [J_3, O^s_{\lambda}] = \lambda O^s_{\lambda}, \\ [J_{\pm}, O^s_{\lambda}] &= \sqrt{s(s+1) - \lambda(\lambda \pm 1)}O^s_{\lambda \pm 1}. \end{aligned}$$
(5)

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Proof: For infinitesimal $R_I(\delta\psi)$, $U_IO_{\lambda}^{s}U_I^{-1} \simeq O_{\lambda}^{s} - i\delta\psi[J_I, O_{\lambda}^{s}]$ and $D_s(R)^{\lambda'}{}_{\lambda}\delta_{\lambda}^{\lambda'} - i\delta\psi(J_I^{s})^{\lambda'}{}_{\lambda}$, hence $[J_I, O_{\lambda}^{s}] = O_{\lambda'}^{s}(J_I^{s})^{\lambda'}{}_{\lambda}$.

- ▶ **Def:** { A_l , l = 1, 2, 3} are the *Cartesian components of a vector* if $[J_k, A_l] = i\varepsilon_{klm}A_m$.
- ▶ **Def:** { $T_{l_1...l_n}$; $l_i = 1, 2, 3$ } are the components of an *n*-th rank tensor if [J_k , $T_{l_1...l_n}$] = $i(\varepsilon_{kl_1m}T_{ml_2...l_n} + \cdots + \varepsilon^{kl_nm}T_{l_1...l_{n-1}m})$.

II.2.14. Wigner-Eckart theorem

According to the W-E theorem,

$$\langle j'm'|O_{\lambda}^{s}|jm\rangle = \langle j'm'(s,j)\lambda m\rangle \langle j'||O^{s}||j\rangle, \qquad (6)$$

where $\langle j' || O^s || j \rangle$ is independent of m, m' and λ .

- ► The selection rules imply that the matrix elements vanish unless $|j s| \le j' \le j + s$ and $m' = \lambda + m$.
- The branching ratios are determined completely by C-G coefficients:

$$\frac{\langle j'm'|O_{\lambda}^{s}|jm\rangle}{\langle j'n'|O_{\sigma}^{s}|jn\rangle} = \frac{\langle j'm'(s,j)\lambda m\rangle}{\langle j'n'(s,j)\sigma n\rangle}.$$
(7)

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Example: Dipole selection rules

A particle in a weak external electromagnetic field is described by

$$H = \frac{\pi^2}{2m} + V(r) + qU, \qquad \pi = \mathbf{p} - q\mathbf{A}, \quad \mathbf{p} = -i\hbar\boldsymbol{\nabla}.$$
 (8)

▶ Taking U = 0 and the Coulomb gauge, $\nabla \cdot \mathbf{A} = 0$, we have

$$H \simeq H_0 + H_I, \quad H_I = -\frac{q}{m} \mathbf{A} \cdot \mathbf{p} = \frac{iq}{\hbar} \mathbf{A} \cdot [\mathbf{x}, H_0].$$
 (9)

▶ Writing $\mathbf{A} = \mathbf{A}_0 e^{-i(\omega t - \mathbf{k} \cdot \mathbf{x})} \simeq \mathbf{A}_0 e^{-i\omega t}$ (when $\mathbf{k} \cdot \mathbf{r} \ll 1 \equiv$ dipole approximation, the transition matrix $T_{i \to f} = \langle f | H_I | i \rangle$ reduces to

$$\langle f|H_I|i\rangle = -\frac{q\omega_{fi}}{\omega}\mathbf{E}\cdot\langle f|\mathbf{x}|i\rangle, \quad \mathbf{E}=-\partial_t\mathbf{A}=i\omega\mathbf{A}, \quad \hbar\omega_{fi}=E_f-E_i.$$

• Taking now $|i\rangle = |nlm\rangle$ and $|f\rangle = |n'l'm'\rangle$, W-E gives

$$\langle n'l'm'|X_{\lambda}^{1}|nlm\rangle = \langle l'm'(1l)\lambda m\rangle \langle n'l'||X^{1}||nl\rangle.$$
(10)

▶ If $\mathbf{E} = E\mathbf{k}$, then $\mathbf{E} \cdot \mathbf{x} = EX_0$ and m' = m.

- If **E** is in the x y plane, then $m' = m \pm 1$.
- From the CG series, l' l = 0 or ± 1 .

Since $\mathbf{L} = \mathbf{x} \times \mathbf{p}$, $\mathbf{x} \cdot \mathbf{L} = 0$ and

$$\langle Im | \mathbf{x} \cdot \mathbf{L} | Im \rangle = \sum_{l',m'} \langle Im | \mathbf{x} | l'm' \rangle \cdot \langle l'm' | \mathbf{L} | Im \rangle = 0.$$
 (11)

• Considering that $\mathbf{x} \cdot \mathbf{L} = \sum_{M=-1}^{1} (-1)^{M} X_{M}^{1} L_{-M}^{1}$, with

$$X_{-1}^{1} = \frac{x - iy}{\sqrt{2}}, \quad X_{0}^{1} = z, \quad X_{1}^{1} = -\frac{x + iy}{\sqrt{2}},$$
 (12)

and similarly for L^1_{λ} , we have

$$0 = \sum_{l',m',M} (-1)^M \langle lm(1l')Mm' \rangle \langle l'm'(1l) - M, m \rangle \langle l||X^1||l' \rangle \langle l'||L^1||l \rangle.$$
(13)

• Since
$$\langle l'm'|L^1_{\lambda}|lm\rangle \simeq \delta_{ll'}\delta_{m',m+\lambda}$$
, we have

$$0 = \sum_{M=-1}^{1} (-1)^{M} \left\langle \textit{Im}(1\textit{I})M, m + M \right\rangle \left\langle \textit{I}, m + M(1\textit{I}) - M, m \right\rangle$$

 $\times \langle I || X^{1} || I \rangle \langle I || L^{1} || I \rangle .$ (14)

► The sum over the CG coefficients is not zero and $\langle I || L^1 || I \rangle \neq 0 \Rightarrow \langle I || X^1 || I \rangle = 0$, leading to $(\mathbf{E} = E\mathbf{k})$:

$$\langle n'l'm'|H_l|nlm\rangle = -\frac{qE\omega_{fi}}{\omega} [\delta_{l',l+1}\langle l+1m(1l)0m\rangle\langle n'l+1||X^1||nl\rangle \\ +\delta_{l',l-1}\langle l-1m(1l)0m\rangle\langle n'l-1||X^1||nl\rangle].$$

II.3. The group SU(2)

II.3.1. Parametrization of SU(2) matrices

- SU(2) is the group of complex, unitary matrices of size 2.
- ▶ Theorem: An arbitrary 2 × 2 unitary matrix can be parametrized as

$$U = e^{i\lambda} \begin{pmatrix} \cos\theta e^{i\zeta} & -\sin\theta e^{i\eta} \\ \sin\theta e^{-i\eta} & \cos\theta e^{-i\zeta} \end{pmatrix}, \qquad \begin{array}{l} 0 \leq \zeta, \eta < 2\pi, \\ 0 \leq \lambda < \pi, \\ 0 \leq \theta \leq \pi/2. \end{array}$$
(15)

Proof: Can be verified by explicit construction. Additionally, a 2×2 complex matrix has a total of 8 real dofs, 4 of which are fixed by $U^{\dagger}U = E$. The remaining 4 parametrize Eq. (15) and their ranges is established as follows:

- ζ and η cover the entire circle;
- θ covers the first quadrant, as the other quadrants can be obtained by changing the sign of either cos θ or sin θ by suitable choices of the phases ζ and η;
- The overall phase λ covers the upper two quadrants, since e^{iπ} = −1 can be absorbed in the phases e^{iζ} and e^{iη}.
- ▶ Imposing now det U = 1 gives $\lambda = 0 \Rightarrow$ an arbitrary SU(2) matrix A can be parametrized using 3 real parameters: θ, η and ζ .

II.3.2. Relationship to SO(3)

The SU(2) matrices and the j = 1/2 representation of SO(3) matrices,

$$A = \begin{pmatrix} \cos\theta e^{i\zeta} & -\sin\theta e^{i\eta} \\ \sin\theta e^{-i\eta} & \cos\theta e^{-i\zeta} \end{pmatrix}, \ D^{1/2}(\alpha,\beta,\gamma) = \begin{pmatrix} e^{-\frac{i}{2}(\alpha+\gamma)}\cos\frac{\beta}{2} & -e^{-\frac{i}{2}(\alpha-\gamma)}\sin\frac{\beta}{2} \\ e^{\frac{i}{2}(\alpha-\gamma)}\sin\frac{\beta}{2} & e^{\frac{i}{2}(\alpha+\gamma)}\cos\frac{\beta}{2} \end{pmatrix},$$
(16)

are identical provided

$$\theta = \frac{\beta}{2}, \quad \zeta = -\frac{\alpha + \gamma}{2}, \quad \eta = -\frac{\alpha - \gamma}{2}.$$
(17)

• Clearly,
$$0 \le \beta < \pi$$
.

► To fully cover SU(2), $0 \le \zeta$, $\eta < 2\pi$, $0 \le \alpha < 2\pi$ and $0 \le \gamma < 4\pi$.

- Since γ covers the circle twice, the SU(2) matrices form a double-valued rep. of SO(3).
- Any SU(2) matrix can be represented in the angle-axis p.:

$$A_{\mathbf{n}}(\psi) = e^{-\frac{i}{2}\psi\mathbf{n}\cdot\boldsymbol{\sigma}} = \begin{pmatrix} \cos\frac{\psi}{2} - i\sin\frac{\psi}{2}\cos\theta & -i\sin\frac{\psi}{2}\sin\theta e^{-i\varphi} \\ -i\sin\frac{\psi}{2}\sin\theta e^{i\varphi} & \cos\frac{\psi}{2} + i\sin\frac{\psi}{2}\cos\theta \end{pmatrix}.$$

► Using Euler angles, $A(\alpha, \beta, \gamma) = e^{-\frac{i}{2}\alpha\sigma_3}e^{-\frac{i}{2}\beta\sigma_2}e^{-\frac{i}{2}\gamma\sigma_3}$, where

$$A_3(\psi) = \begin{pmatrix} e^{-\frac{i}{2}\psi} & 0\\ 0 & e^{\frac{i}{2}\psi} \end{pmatrix}, \qquad A_2(\psi) \equiv d_{1/2}(\psi) = \begin{pmatrix} \cos\frac{\psi}{2} & -\sin\frac{\psi}{2}\\ \sin\frac{\psi}{2} & \cos\frac{\psi}{2} \end{pmatrix}.$$

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II.3.3 Invariant integration measure

Integrations over the group elements must be compatible with the rearrangement lemma:

$$\int f(A) d\tau_A = \int f(B^{-1}A') d\tau_{B^{-1}A'} = \int f(B^{-1}A') d\tau_{A'}, \quad (18)$$

with A' = BA.

 Using generic {ξ, η, ζ} to parametrize de group elements, we seek a weight function ρ such that

$$d\tau_{A} = \rho(\xi, \eta, \zeta) d\xi d\eta d\zeta = \rho(\xi', \eta', \zeta') d\xi' d\eta' d\zeta',$$
(19)

where $\{\xi',\eta',\zeta'\}$ corresponds to ${\it A}'={\it B}{\it A},$ and

$$\frac{\rho(\xi,\eta,\zeta)}{\rho(\xi',\eta',\zeta')} = \frac{\partial(\xi',\eta',\zeta')}{\partial(\xi,\eta,\zeta)}.$$
(20)

The above equation becomes easy when (ξ', η', ζ') are linear functions of (ξ, η, ζ).

• The overall normalization is chosen such that $\int d\tau_A = 1$.

Consider the parametrization of an SU(2) matrix via

$$A = \begin{pmatrix} r_0 - ir_3 & -r_2 - ir_1 \\ r_2 - ir_1 & r_0 + ir_3 \end{pmatrix}, \quad \det A = r_0^2 + \mathbf{r}^2 = 1.$$
(21)

• The real parameters $r_0, \ldots r_3$ are connected to θ, ζ, η and an extra parameter r via

$$\begin{pmatrix} r_0 \\ r_3 \end{pmatrix} = r \cos \theta \begin{pmatrix} \cos \zeta \\ -\sin \zeta \end{pmatrix}, \quad \begin{pmatrix} r_1 \\ r_2 \end{pmatrix} = r \sin \theta \begin{pmatrix} \sin \eta \\ -\cos \eta \end{pmatrix}, \quad (22)$$

such that det $A = r^2 = 1$.

Consider now r_i and r'_i, parametrizing A and A', and s_i, parametrizing B, such that A' = BA. The Jacobian of the transformation is:

$$\frac{\partial(r'_0, r'_1, r'_2, r'_3)}{\partial(r_0, r_1, r_2, r_3)} = \begin{vmatrix} s_0 & -s_1 & -s_2 & -s_3 \\ s_1 & s_0 & -s_3 & s_2 \\ s_2 & s_3 & s_0 & -s_1 \\ s_3 & -s_2 & s_1 & s_0 \end{vmatrix} = (s_0^2 + \mathbf{s}^2)^2 = 1, \quad (23)$$

which means $dr_0 dr_1 dr_2 dr_3 = dr'_0 dr'_1 dr'_2 dr'_3$.

lmposing det A = 1, the integration measure can be taken as

$$V_G d\tau_A = d^4 r \,\delta(1 - r_0^2 - \mathbf{r}^2) = \frac{d^4 r}{2\sqrt{1 - \mathbf{r}^2}} \sum_{\varsigma = \pm 1} \delta(r_0 - \varsigma \sqrt{1 - \mathbf{r}^2}), \quad (24)$$

where $d^4r = dr_0 dr_1 dr_2 dr_3$, while V_G is a normalization constant:

$$V_G = \int d^4 r \delta(1 - r_0^2 - \mathbf{r}^2) = 4\pi \int_0^1 \frac{dr r^2}{\sqrt{1 - r^2}} = \pi^2.$$
 (25)

• With respect to (r, θ, ζ, η) , we have

$$d\tau_{A} = \frac{\delta(1-r^{2})}{\pi^{2}} \frac{\partial(r_{0}, r_{1}, r_{2}, r_{3})}{\partial(r, \theta, \zeta, \eta)} dr d\theta d\zeta d\eta \rightarrow \frac{\sin(2\theta)}{4\pi^{2}} d\theta d\zeta d\eta.$$
(26)

W.r.t. the Euler angle and angle-axis parametrizations,

$$SU(2): \qquad d\tau_{A} = \frac{d\alpha d\cos\beta d\gamma}{16\pi^{2}} = \sin^{2}\frac{\psi}{2}\frac{d\psi d\cos\theta d\phi}{4\pi^{2}},$$

$$SO(3): \qquad d\tau_{R} = \frac{d\alpha d\cos\beta d\gamma}{8\pi^{2}} = \sin^{2}\frac{\psi}{2}\frac{d\psi d\cos\theta d\phi}{2\pi^{2}}, \qquad (27)$$

where $0 \le \gamma < 4\pi$ for SU(2) and $0 \le \gamma < 2\pi$ for SO(3); For angle-axis, we use $0 \le \phi < 2\pi$, $0 \le \theta \le \pi$ and $0 \le \psi < 2\pi$ for SU(2) and $0 \le \psi < \pi$ for SO(3).

II.3.4. Orthonormality of the representation matrices

- ▶ In the case of discrete groups, $\frac{n_{\mu}}{n_{c}}\sum_{g} D^{\dagger}_{\mu}(g)^{k}{}_{i}D_{\nu}(g)^{j}{}_{i} = \delta_{\mu\nu}\delta^{k}_{i}\delta^{j}_{i}$.
- ▶ For SU(2), irrep j has size $n_{\mu} \rightarrow n_j = 2j + 1$ and

$$(2j+1)\int d\tau_{A}D_{j}^{\dagger}(A)^{m}{}_{n}D_{j'}(A)^{n'}{}_{m'} = \delta_{jj'}\delta^{m}{}_{m'}\delta^{n'}{}_{n}.$$
 (28)

Using the Euler angle parametrization, the α and γ integrations can be performed, giving (no summation over n, m):

$$\frac{2j+1}{2}\int_{-1}^{1}d(\cos\beta)d_{j}(\beta)^{n}{}_{m}d_{j'}(\beta)^{n}{}_{m}=\delta_{jj'}.$$
(29)

• Multiplying Eq. (28) by $\delta_m^n \delta_{n'}^{m'}$ gives

$$\int d\tau_A \chi_j^{\dagger}(A) \chi_{j'}(A) = \delta_{jj'}.$$
(30)

• Using $\chi_j(A) = \sin[(j + \frac{1}{2})\psi] / \sin\frac{\psi}{2}$, we have

$$\int d\tau_A \chi_j^{\dagger}(A) \chi_{j'}(A) = \int_0^{2\pi} \frac{d\psi}{2\pi} \left(\cos[(j-j')\psi] - \cos[(j+j'+1)\psi] \right) = \delta_{jj'}.$$

II.3.5. Completeness: Peter-Weyl theorem

- Theorem (Peter-Weyl): The irrep functions D_i(A)^m_n form a complete basis in the space of (Lebesgue) square-integrable functions defined on the group manifold.
- Let f(A) be such a function, then:

$$f(A) = \sum_{jmn} f_{jm}^n D_j(A)^m{}_n, \quad f_{jm}^n = (2j+1) \int d\tau_A D_j^{\dagger}(A)^n{}_m f(A),$$
 (31)

which implies

$$\sum_{jmn} (2j+1) D_j(A)^m{}_n D_j^{\dagger}(A')^n{}_m = \delta(A-A'),$$
(32)

where $\delta(A - A') = 16\pi^2 \delta(\alpha - \alpha') \delta(\cos \beta - \cos \beta') \delta(\gamma - \gamma')$ in the Euler angle parametrization.

- ▶ Bose-Einstein: $f(\alpha, \beta, \gamma + 2\pi) = f(\alpha, \beta, \gamma)$ and $f_{jm}^n = 0$ when $j = l + \frac{1}{2}$.
- Fermi-Dirac: $f(\alpha, \beta, \gamma + 2\pi) = -f(\alpha, \beta, \gamma)$ and $f_{jm}^n = 0$ when j = I.
- ▶ In the case when $f(\alpha, \beta, \gamma)$ is independent of γ , denoting $(\alpha, \beta) \rightarrow (\phi, \theta)$, we write

$$f(heta,\phi) = \sum_{l=0}^{\infty} \sum_{m=-l}^{l} f_{lm} Y_{lm}(heta,\phi), \quad Y_{lm}(heta,\phi) = \sqrt{rac{2l+1}{4\pi}} D_l^*(\phi, heta,0)^m_0,$$

and $f_{lm} = \int d\cos\theta d\phi Y^*_{lm}(\theta,\phi) f(\theta,\phi)$.

II.3.6. Projection operators

The invariant integration measure allows the projection operators to be constructed:

$$P_{jm}^{n} = (2j+1) \int d\tau_{A} D_{j}^{\dagger}(A)^{n}{}_{m} U(A), \qquad (33)$$

by which $P_{jm}^n \ket{j'm'} = \ket{j'm'} \delta_j^{j'} \delta_{m'}^n$.

II.3.7. Differential equation for D_i

For
$$R(\alpha, \beta, \gamma) = e^{-i\alpha J_3} e^{-i\beta J_2} e^{-i\gamma J_3}$$
, we have
 $i \frac{\partial R}{\partial \alpha} = R[R^{-1}J_3R], \quad i \frac{\partial R}{\partial \beta} = R[e^{i\gamma J_3}J_2e^{-i\gamma J_3}], \quad i \frac{\partial R}{\partial \gamma} = RJ_3.$ (34)

• Using $R^{-1}J_iR = R_i^jJ_j$, the square brackets evaluate to

$$R^{-1}J_{3}R = -\frac{\sin\beta}{2}(J_{+}e^{i\gamma} + J_{-}e^{-i\gamma}) + J_{3}\cos\beta,$$

$$e^{i\gamma J_{3}}J_{2}e^{-i\gamma J_{3}} = \frac{i}{2}(-J_{+}e^{i\gamma} + J_{-}e^{-i\gamma}).$$
 (35)

Plugging Eq. (35) into Eq. (34) gives

$$e^{-i\gamma} \left[-\frac{\partial}{\partial\beta} - \frac{i}{\sin\beta} \left(\frac{\partial}{\partial\alpha} - \cos\beta \frac{\partial}{\partial\gamma} \right) \right] R = RJ_{+},$$

$$e^{i\gamma} \left[\frac{\partial}{\partial\beta} - \frac{i}{\sin\beta} \left(\frac{\partial}{\partial\alpha} - \cos\beta \frac{\partial}{\partial\gamma} \right) \right] R = RJ_{-}, \quad i\frac{\partial R}{\partial\gamma} = RJ_{3}.$$
(36)

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• Evaluating $\langle jm' | RJ_{\pm} | jm \rangle$ gives

$$\left(-\frac{d}{d\beta} - \frac{m' - m\cos\beta}{\sin\beta}\right) d_j(\beta)^{m'}{}_m = d_j(\beta)^{m'}{}_{m+1}\sqrt{j(j+1) - m(m+1)},$$

$$\left(\frac{d}{d\beta} - \frac{m' - m\cos\beta}{\sin\beta}\right) d_j(\beta)^{m'}{}_m = d_j(\beta)^{m'}{}_{m-1}\sqrt{j(j+1) - m(m-1)}.$$

$$(37)$$

- The above relations can be used as recurrence relations: Knowing d_j(β)^{m'}_m for a combination of m and m', it is possible to obtain it for all other m.
- At the same time, a differential eq. can be obtained for $d_j(\beta)^{m'}{}_m$ by applying $\mathbf{J}^2 = J_3^2 J_3 + J_+J_-$, since:

$$R\mathbf{J}^{2} = \left\{ e^{-i\gamma} \left[-\frac{d}{d\beta} - \frac{i}{\sin\beta} \left(\frac{\partial}{\partial\alpha} - \cos\beta \frac{\partial}{\partial\gamma} \right) \right] \\ \times e^{i\gamma} \left[\frac{\partial}{\partial\beta} - \frac{i}{\sin\beta} \left(\frac{\partial}{\partial\alpha} - \cos\beta \frac{\partial}{\partial\gamma} \right) \right] - \frac{\partial^{2}}{\partial\gamma^{2}} - i \frac{\partial}{\partial\gamma} \right\} R.$$
(38)

• Using $\langle jm'|R\mathbf{J}^2|jm\rangle = j(j+1)e^{-i\alpha m'-i\gamma m}d_j(\beta)^{m'}{}_m$ leads to

$$\left(\frac{1}{\sin\beta}\frac{d}{d\beta}\sin\beta\frac{d}{d\beta}-\frac{m^2+m'^2-2mm'\cos\beta}{\sin^2\beta}+j(j+1)\right)d_j(\beta)^{m'}{}_m=0.$$

II.3.8. Relation to spherical harmonics

▶ When
$$m = 0$$
, setting $(m', j, \beta) \rightarrow (m, l, \theta)$ and restoring $D_l(\phi, \theta, 0)^m_0 = e^{-im\phi} d_l(\theta)^m_0$ gives

$$\left[\frac{1}{\sin\theta}\frac{\partial}{\partial\theta}\sin\theta\frac{\partial}{\partial\theta}+\frac{1}{\sin^2\theta}\frac{\partial^2}{\partial\phi^2}+I(I+1)\right]D_I(\phi,\theta,0)^m{}_0=0,\qquad(40)$$

which is solved by the spherical harmonics:

$$[D_{l}(\phi,\theta,0)^{m}_{0}]^{*} = \sqrt{\frac{4\pi}{2l+1}} Y_{lm}(\theta,\phi), \quad d_{l}(\theta)^{m}_{0} = \sqrt{\frac{(l-m)!}{(l+m)!}} (-1)^{m} P_{lm}(\theta).$$
(41)

▶ For general (*m*, *m*′), the differential eq. can be put in the form for the Jacobi polynomials,

$$\left\{ (1-z^2)\frac{d^2}{dz^2} + [\beta - \alpha - (2+\alpha+\beta)z]\frac{d}{dz} + l(l+\alpha+\beta+1) \right\} P_l^{(\alpha,\beta)}(z) = 0,$$
(42)

such that

$$d_{j}(\beta)^{m'}{}_{m} = \sqrt{\frac{(j+m')!(j-m')!}{(j+m)!(j-m)!}} \left(\cos\frac{\beta}{2}\right)^{m+m'} \left(\sin\frac{\beta}{2}\right)^{m-m'} P_{j-m'}^{m'-m,m'+m}(\cos\beta).$$
(43)

This reproduces the m = 0 result since

$$P_{l-m}^{m,m}(z) = (-2)^m \frac{l!}{(l-m)!} (1-z^2)^{-m/2} P_{lm}(z),$$
(44)

as well as $P_l(\cos\theta) = P_{l0}(\cos\theta) = P_l^{0,0}(\cos\theta) = d_l(\theta)_0^0$.

II.3.9. Properties of spherical harmonics

Transformation under rotations: Consider $|\xi,\psi\rangle = U(\alpha,\beta,\gamma) |\theta,\phi\rangle$. Then:

$$Y_{lm}(\theta,\phi) = \langle \xi,\psi | U(\alpha,\beta,\gamma) | lm \rangle = Y_{lm'}(\xi,\psi) D_l(\alpha,\beta,\gamma)^{m'}{}_m.$$
(45)

• Addition theorem: Taking m = 0 and using $Y_{l0}(\theta, \phi) = P_l(\cos \theta)\sqrt{(2l+1)/4\pi}$, such that

$$\sum_{m'} Y_{lm'}(\xi, \psi) Y_{lm'}(\beta, \alpha) = \frac{2l+1}{4\pi} P_l(\cos \theta),$$
(46)

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where $\cos \theta = \mathbf{n}(\xi, \psi) \cdot \mathbf{n}(\beta, \alpha)$.

Decomposition of products of Y_{lm} with the same arguments:

$$Y_{lm}(\theta,\phi)Y_{l'm'}(\theta,\phi) = \sum_{L} \langle mm'(ll')Lm + m' \rangle Y_{L,m+m'}(\theta,\phi) \\ \times \langle L0(ll')00 \rangle \sqrt{\frac{(2l+1)(2l'+1)}{4\pi(2L+1)}}.$$
 (47)

Symmetry in *m*: $Y_{l,-m}(\theta,\phi) = (-1)^m Y_{lm}^*(\theta,\phi)$.

Eqs. (37) provide recurrence relations at fixed /:

$$\sqrt{I(I+1) - m(m+1)} Y_{l,m+1}(\theta,\phi) = e^{i\phi} \left(\frac{d}{d\theta} - m\cot\theta\right) Y_{lm}(\theta,\phi),$$
$$\sqrt{I(I+1) - m(m-1)} Y_{l,m-1}(\theta,\phi) = e^{-i\phi} \left(-\frac{d}{d\theta} - m\cot\theta\right) Y_{lm}(\theta,\phi).$$
(48)

• Recurrence relations at fixed *m* can be obtained by multiplying $Y_{lm}Y_{10}$, with $Y_{10}(\theta, \phi) = \cos \theta \sqrt{3/4\pi}$:

$$\cos\theta Y_{lm}(\theta,\phi) = \sqrt{\frac{(l+m)(l-m)}{(2l-1)(2l+1)}} Y_{l-1,m}(\theta,\phi) + \sqrt{\frac{(l+m+1)(l-m+1)}{(2l+1)(2l+3)}} Y_{l+1,m}(\theta,\phi), \quad (49)$$

where we used:

$$\langle m0(l1)l + 1m \rangle = \sqrt{\frac{(l-m+1)(l+m+1)}{(2l+1)(l+1)}}, \quad \langle m0(l1)lm \rangle = \frac{m}{\sqrt{l(l+1)}},$$

$$\langle m0(l1)l - 1m \rangle = -\sqrt{\frac{(l-m)(l+m)}{l(2l+1)}}.$$
(50)

• **Orthogonality:** $\int d\Omega Y_{lm}^*(\theta, \phi) Y_{l'm'}(\theta, \phi) = \delta_{ll'} \delta_{mm'}$.

• **Completeness:** $\sum_{l,m} Y_{lm}(\theta,\phi) Y^*_{lm}(\theta',\varphi') = \delta(\cos\theta - \cos\theta')\delta(\phi - \phi').$

Exercises

1. Starting from the commutation relations $[J_i, X_j] = i\varepsilon_{ijk}X_k$, show that the components of the irreducible vector operator X_{λ}^1 are:

$$X_0^1 = X_3, \qquad X_{\pm 1}^1 = \frac{1}{\sqrt{2}} (\mp X_1 - iX_2).$$

WKT7.9 If { T_{ij} , i, j = 1, 2, 3} are the components of a second-rank tensor, show that: (i) tr $T = \delta^{ij} T_{ij}$ is invariant under SO(3); (ii) $\hat{T}_{ij} = (T_{ij} - T_{ji})/2$ remains antisymmetric after an SO(3) transformation, and $\hat{T}_k = \frac{1}{2} \varepsilon_{kij} T_{ij}$ transforms as a vector; (iii) $\tilde{T}_{ij} = (T_{ij} + T_{ji})/2 - \frac{1}{3} \delta_{ij} \text{tr} T$ remains symmetric under SO(3) and the 5 independent components of \tilde{T} transform with the j = 2 representation.

2. Derive the invariant integration measure for SU(2) with respect to the parameters θ, ζ, η , shown in Eq. (26). [Hint: multiply A in Eq. (16) by a factor r and impose at the end r = 1 via a Dirac delta function]

Exercises

3. Derive the invariant integration measure with respect to the angle-axis parameters, using the convention $0 \le \phi < 2\pi$, $0 \le \theta \le \pi/2$ and $0 \le \psi < 4\pi$ for SU(2). Use the explicit relation between the angle-axis parameters and the Euler angles:

$$\phi = \frac{\pi + \alpha - \gamma}{2}, \quad \tan \theta = \frac{\tan(\beta/2)}{\sin[(\gamma + \alpha)/2]}, \quad \cos \frac{\psi}{2} = \cos\left(\frac{\beta}{2}\right) \cos\left(\frac{\alpha + \gamma}{2}\right).$$

4. Completeness of characters.

a) Use Schur's lemma to show that $A_{\psi}^{j} = \int \frac{d\Omega_{n}}{4\pi} D_{j}[R_{n}(\psi)] = c_{\psi}^{j}E$, where E is the identity matrix.

b) Using the angle-axis parametrization of the SU(2) matrices A and A', integrate Eq. (32) with respect to $d\Omega_{n'} = d(\cos \theta')d\phi'$ to show that:

$$\sin^2 \frac{\psi}{2} \sum_j \chi_j(\psi) \chi_j(\psi') = \pi \delta(\psi - \psi').$$
(51)

c) Therefore deduce that $\sum_{j=0}^{\infty} \frac{1}{2j+1} \sin[\psi(j+\frac{1}{2})] = \frac{\pi}{4}$.

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Exercises

- Invariant integration measure. Consider the parametrization (θ, ζ, η) of the SU(2) matrices in Eq. (16).
 - a) Calculate $\partial A/\partial_{\xi_i}$, with $\xi_i = \{\theta, \zeta, \eta\}$.

b) Express the product $A^{-1}(\xi)(\partial A/\partial \xi_i)$ with respect to the generators J_{α} , using the matrix \widetilde{A} defined below:

$$A^{-1}\frac{\partial A}{\partial \xi_i} = \sum_{\alpha} J_{\alpha} \widetilde{A}(\xi)^{\alpha}{}_i.$$
(52)

c) Compute $d\tau_A = \rho_A(\xi) \prod_i d\xi_i$, with $\rho_A(\xi) = \det \widetilde{A}(\xi)^{\alpha}_i$.

- d) Repeat the above for the angle-axis parametrization.
- 6. Reduced representation matrix $d_j(\beta)$. Consider the direct product of *n* irreducible representations with j = 1/2. Of these, consider the basis $|jm\rangle$ corresponding to the j = n/2 (maximal) irrep.

a) Show that
$$|jj\rangle = |++\cdots+\rangle$$
.

b) By repeated application of J_{-} , show that

$$|jm\rangle = \sqrt{\frac{(j-m)!(j+m)!}{(2j)!}} \underbrace{(\underbrace{j+m \text{ elements } j-m \text{ el. }}_{(2j)!/[(j+m)!(j-m)!] \text{ terms }}} j+m \text{ el. }_{j+m \text{ el. }} \underbrace{j+m \text{ el. }}_{(2j)!/[(j+m)!(j-m)!] \text{ terms }} j+m \text{ el. }}_{(2j)!/[(j+m)!(j-m)!] \text{ terms }} j+m \text{ el. }}$$

c) Show that $U_2(\beta) |\pm\rangle = |\pm\rangle c \pm |\mp\rangle s$, where $c = \cos(\beta/2)$ and $s = \sin(\beta/2)$. d) Taking into account that $|jm\rangle$ and $U_2(\beta) |jm\rangle$ are totally symmetric, show that

$$\langle jm' | U_2(\beta) | jm \rangle = \sum_{k=0}^{j-m} (-1)^k \frac{\sqrt{(j+m)!(j-m)!(j+m')!(j-m')!}}{k!(j+m'-k)!(m-m'+k)!(j-m-k)!} \times c^{2j-2k-m+m'} s^{2k+m-m'}.$$
 (53)