Applications of the Laguerre lattice Boltzmann models to Couette flow

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Lattice Boltzmann modelling

- The lattice Boltzmann method is a numerical method for solving the Boltzmann equation.
- The Boltzmann equation is useful when the Knudsen number $Kn = \lambda/l$ is non-negligible (mezoscopic scale).
- At Kn → 0, the Boltzmann equation reduces to the Navier-Stokes-Fourier equations.
- When Kn > 0.01, microfluidics effects become noticeable.
- Lattice Boltzmann models provide a way to discretise the momentum space over which the Boltzmann distribution function is defined.
- Gauss-Laguerre quadrature methods can be used to implement diffuse reflective boundaries.
- Couette flow is important for testing the validity of numerical models due to its relative simplicity and to the existence of analytic results.

Boltzmann Equation

• Evolution equation of the one-particle distribution function $f \equiv f(\mathbf{x}, \mathbf{p})$

 $\partial_t f + \frac{1}{m} p_\alpha \partial_\alpha f = J[f], \qquad J \text{ describes inter-particle collisions}$

• Hydrodynamic moments give macroscopic quantities:

number density:

$$n = \int d^{3}pf,$$
velocity:

$$\mathbf{u} = \frac{1}{nm} \int d^{3}pf \,\mathbf{p},$$
temperature:

$$T = \frac{1}{3nm} \int d^{3}pf \,\xi^{2}, \quad (\xi = \mathbf{p} - m\mathbf{u}),$$
heat flux:

$$\mathbf{q} = \frac{1}{2m^{2}} \int d^{3}pf \,\xi^{2} \,\xi.$$

Shakhov collision term and macroscopic equations

• For fluids at Pr = 2/3, the Shakhov collision term must be used:

$$J[f] = -\frac{1}{\tau} \left[f - f^{(\text{eq})}(1 + \mathbb{S}) \right], \quad \tau = \frac{\text{Kn}}{n} \text{ is the relaxation time,}$$
$$\mathbb{S} = \frac{1 - \Pr}{nT^2} \left[\frac{\xi^2}{(D+2)mT} - 1 \right] \xi \cdot \mathbf{q}$$

• $f^{(eq)}$ is the Maxwell-Boltzmann distribution function:

$$f^{(\text{eq})} = \frac{n}{(2\pi mT)^{D/2}} \exp\left(-\frac{\xi^2}{2mT}\right) \qquad (\xi = \mathbf{p} - m\mathbf{u})$$

 Through the Chapman-Enskog expansion, the recovery of the Navier-Stokes-Fourier equations requires moments of up to order 6 of f^(eq).

Boundary conditions for the distribution function

Due to the particle – wall interaction, reflected particles carry some information that belongs to the wall.



bounce back



specular reflection



diffuse reflection

diffuse reflection the distribution function of *reflected* particles is identical to the Maxwellian distribution function $f^{(eq)}(\mathbf{u}_{wall}, T_{wall})$ microfluidics $Kn = \lambda/L$ is non-negligible \Rightarrow velocity slip u_{slip} \Rightarrow temperature jump T_{jump}

Diffuse reflection boundary conditions

• The diffuse reflection boundary conditions require:

$$f(\mathbf{x}_{\mathrm{w}},\mathbf{p},t) = f^{(\mathrm{eq})}(n_{\mathrm{w}},\mathbf{u}_{\mathrm{w}},T_{\mathrm{w}}) \qquad (\mathbf{p}\cdot\chi<0),$$

where χ is the outwards-directed normal to the boundary.

• The density *n*_w is fixed by the requirement of zero flux through the boundary:

$$\int_{\mathbf{p}\cdot\chi>0} d^3p f\left(\mathbf{p}\cdot\chi\right) = -\int_{\mathbf{p}\cdot\chi<0} d^3p f^{(\text{eq})}\left(\mathbf{p}\cdot\chi\right).$$

 Diffuse reflection requires the computation of integrals of *f*^(eq) over half of the momentum space.

Application: Couette flow

- flow between parallel plates moving along the *y* axis
- $x_t = -x_b = 0.5$
- Velocity of plates: $u_t = -u_b = 0.42$
- Temperature of plates: $T_b = T_t = 1.0$
- Diffuse reflection boundary conditions on the *x* axis



Simulations done using PETSc 3.1 at:

- NANOSIM cluster collaboration with Prof. Daniel Vizman, West University of Timişoara, Romania
- IBM-SP6, CINECA collaboration with Prof. Giuseppe Gonnella, University of Bari, Italy
- MATRIX system, CASPUR collaboration with dr. Antonio Lamura, IAC-CNR, Section of Bari, Italy
- BlueGene cluster collaboration with Prof. Daniela Petcu, West University of Timişoara, Romania

Cartesian and spherical coordinates: HLB and SLB

• HLB is based on Hermite quadratures on the Cartesian axes:

$$\int_{-\infty}^{\infty} dp_{\alpha} f^{(\text{eq})}(p_{\alpha}) p_{\alpha}^{n} \to \sum_{k=1}^{Q_{\alpha}} f_{k}^{(\text{eq})} p_{\alpha,k}^{n}.$$

• SLB recovers moments using spherical coordinates:

$$\int_0^\infty p^2 dp \int_{-1}^1 d\cos\theta \int_0^{2\pi} d\varphi f^{(\text{eq})} P(p,\theta,\varphi) \\ \to \sum_{k,j,i} f_{kji}^{(\text{eq})} P(p_k,\theta_k,\varphi_k).$$

• HLB and SLB are great at recovering full-space moments, but struggle with half-space integrals.



• HLB converges from below, SLB from above, but they struggle to meet.

LLB models and half-space integrals

- Split the momentum space into octants.
- Recover integrals of *f*^(eq) over each octant separately:

$$\int_{-\infty}^{\infty} dp_{\alpha} f^{(\text{eq})}(p_{\alpha}) P(p_{\alpha}) = \int_{0}^{\infty} dp_{\alpha} \left[f^{(\text{eq})}(p_{\alpha}) P(p_{\alpha}) + f^{(\text{eq})}(-p_{\alpha}) P(-p_{\alpha}) \right].$$

 The integration domain [0,∞) is good for Gauss-Laguerre quadrature methods:

$$\int_0^\infty dp_\alpha \, e^{-p_\alpha} P(p_\alpha) = \sum_{k=1}^{Q_\alpha} w_k P(p_{\alpha,k}).$$

• The quadrature points $p_{\alpha,k}$ are the Q_{α} roots of the Laguerre polynomial $L_{Q_{\alpha}}$:

$$L_{Q_\alpha}(|p_{\alpha,k}|)=0.$$

• The quadrature weights w_k are determined by quadrature rules:

$$w_{\alpha,k} = \frac{|p_{\alpha,k}|}{(Q_{\alpha}+1)^2 \left[L_{Q_{\alpha}+1}(|p_{\alpha,k}|)\right]^2}.$$

Expansion of $f^{(eq)}$

• Factorise *f*^(eq) on each coordinate axis:

$$f^{(\rm eq)} = n \, g_x \, g_y \, g_z,$$

where

$$g_{\alpha} \equiv g_{\alpha}(p_{\alpha}; u_{\alpha}, T) = \sqrt{\frac{1}{2\pi mT}} \exp\left[-\frac{(p_{\alpha} - mu_{\alpha})^2}{2mT}\right]$$

• Write g_{α} in terms of the Laguerre polynomials:

$$g_{\alpha} = e^{-|p_{\alpha}|} \sum_{\ell=0}^{N} \mathcal{G}_{\alpha,\ell}(u_{\alpha},T) L_{\ell}(|p_{\alpha}|)$$

- The series is truncated at order *N* for *N*'th order accuracy due to orthogonality properties of the Laguerre polynomials.
- The coefficients can be calculated:

$$\mathcal{G}_{\alpha,\ell} = \frac{1}{2} \sum_{s=0}^{\ell} \frac{(-1)^s}{s!} {\ell \choose s} \left(\frac{mT}{2} \right)^{s/2} \left[(1 + \operatorname{erf} \zeta_{\alpha}) P_s(\zeta_{\alpha}) + \frac{2}{\sqrt{\pi}} e^{-\zeta_{\alpha}^2} P_s^*(\zeta_{\alpha}) \right],$$

where $P_s(\zeta_{\alpha})$ and $P_s^*(\zeta_{\alpha})$ are polynomials of order *s* in $\zeta_{\alpha} = u_{\alpha} \sqrt{m/2T}$.

Discretisation of the momentum space

• The Gauss-Laguerre quadrature gives:

$$\int_{-\infty}^{\infty} dp_{\alpha} f(p_{\alpha}) P_n(p_{\alpha}) \to \sum_{k=1}^{2Q_{\alpha}} e^{|p_{\alpha,k}|} w_{\alpha,k} f(p_{\alpha,k}) P_n(p_{\alpha,k}).$$

• The $2Q_{\alpha}$ momenta and corresponding weights are given by:

$$p_{\alpha,k} = \begin{cases} k' \text{th root of } L_{Q_{\alpha}} & k \leq Q_{\alpha}, \\ -p_{\alpha,k-Q_{\alpha}} & k > Q_{\alpha} \end{cases}, \qquad w_{\alpha,k} = \frac{|p_{\alpha,k}|}{(Q_{\alpha}+1)^2 \left[L_{Q_{\alpha}+1}(|p_{\alpha,k}|)\right]^2}.$$

• Defining $g_{\alpha,k} = w_{\alpha,k}e^{-|p_{\alpha,k}|}g_{\alpha}(p_{\alpha,k})$, the moments of *f* are replaced by:

$$\int d^3 p f P_n(\mathbf{p}) \to \sum_{i=1}^{2Q_x} \sum_{j=1}^{2Q_y} \sum_{k=1}^{2Q_z} f_{ijk} P_n(\mathbf{p}_{ijk}), \qquad f_{ijk} = ng_{x,i}g_{y,j}g_{z,k}.$$

• The Gauss quadrature rules require $Q_{\alpha} > N \Rightarrow 8(N + 1)^3$ momentum vectors required for N'th order accuracy.

LLBN vs SLB: Numeric results for Couette flow at Kn=0.5



Q = 7 (N = 6) needed to recover the NSF equations in the Shakhov model.

 $(u_{walls}=\pm 0.42$, $T_{walls}=1.0$, $\delta s=1/100$, $\delta t=10^{-5}$, Kn=0.5)

Large Kn: ballistic regime

If Kn is large, the collision term goes to 0 and f is determined by boundary conditions:

$$f^{\text{ballistic}}(\mathbf{p}) = \begin{cases} f^{(\text{eq})}(n_b, \mathbf{u}_b, T_b) & p_z > 0\\ f^{(\text{eq})}(n_t, \mathbf{u}_t, T_t) & p_z < 0. \end{cases}$$

The moments are:

$$\begin{split} u_{y} &= -u_{w} \frac{\sqrt{T_{t}} - \sqrt{T_{b}}}{\sqrt{T_{t}} + \sqrt{T_{b}}}, \qquad q_{z} = -n \sqrt{\frac{8T_{t}T_{b}}{m\pi}} (\sqrt{T_{t}} - \sqrt{T_{b}}) \left[1 + \frac{mu_{w}^{2}}{(\sqrt{T_{t}} + \sqrt{T_{b}})^{2}} \right], \\ T &= \sqrt{T_{t}T_{b}}, \left(1 + \frac{4mu_{w}^{2}}{3(\sqrt{T_{t}} + \sqrt{T_{b}})^{2}} \right), \qquad q_{y} = -2nu_{y} \sqrt{T_{t}T_{b}} \left[\frac{5}{2} + \frac{2mu_{w}^{2}}{(\sqrt{T_{t}} + \sqrt{T_{b}})^{2}} \right]. \end{split}$$

N	T	u_y	q_z	q_y
1	2.910987	-0.218165	-6.305084	1.414574
2	3.205209	-0.218187	-11.40061	3.700024
3	3.205209	-0.218187	-11.02230	3.477877
20	3.205209	-0.218187	-11.02229	3.477872
Analytic	3.205209	-0.218187	-11.02227	3.477866

- The Laguerre (LLB) models exhibit good convergence at non-negligible Kn.
- The LLB models recover the ballistic regime very well, even at large temperature differences, where HLB/SLB fail.
- The LLB models are more efficient than HLB/SLB at large enough Kn.
- The LLB models exactly recover half-space fluxes of *f*^(eq) required for the implementation of diffuse reflection boundary conditions.
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